FCC Statements
15.19 – Two Part Warning
This device complies with Part 15 of the FCC rules. Operation is subject to the following two conditions:
(1) This device may not cause harmful interference and
(2) This device must accept any interference received, including interference that may cause undesired operation.

15.21 – Unauthorized Modification
NOTICE: The manufacturer is not responsible for any unauthorized modifications to this equipment made by the user. Such modifications could void the user’s authority to operate the equipment.

Industry Canada Statement
This device complies with Canadian RSS-210.

The installer of this radio equipment must ensure that the antenna is located or pointed such that it does not emit RF field in excess of Health Canada limits for the general population; consult Safety Code 6, obtainable from Health Canada’s website https://www.canada.ca/en/health-canada/services/environmental-workplace-health/reports-publications/radiation/safety-code-6-health-canada-radiofrequency-exposure-guidelines-environmental-workplace-health-health-canada.html.

Industry Canada Statement
This device complies with Industry Canada licence-exempt RSS standard(s). Operation is subject to the following two conditions: (1) this device may not cause interference, and (2) this device must accept any interference, including interference that may cause undesired operation of the device.

Le présent appareil est conforme aux CNR-210 d'Industrie Canada.

RoHS Compliance Statement
Cervis, Inc. complies with the requirements of Restriction of Hazardous Substances (RoHS/WEEE) Specification based on in-house practice and declaration of compliance from our vendors. For additional information concerning RoHS compliance, please contact Cervis, Inc. at:

Cervis, Inc.
170 Thorn Hill Road • Warrendale, PA 15086
Phone: 724.741.9000 • Fax: 724.741.9001

This product may contain material that may be hazardous to human health and the environment. In compliance with EU Directive 2002/96/EC on Waste Electrical and Electronic Equipment (WEEE):

✓ Do not dispose of the product as unsorted municipal waste.
✓ This product should be recycled in accordance with local regulations. Contact local authorities for detailed information.
✓ This product may be returnable to the distributor for recycling. Contact your distributor for details.

IC Unlicensed Devices EIRP Statements for Removable Antennas
Part 1: Under Industry Canada regulations, this radio transmitter may only operate using an antenna of a type and maximum (or lesser) gain approved for the transmitter by Industry Canada. To reduce potential radio interference to other users, the antenna type and its gain should be so chosen that the equivalent isotropically radiated power (e.i.r.p.) is not more than that necessary for successful communication.

Partie 1 : Conformément à la réglementation d'Industrie Canada, le présent émetteur radio peut fonctionner avec une antenne d’un type et d’un gain maximal (ou inférieur) approuvé pour l’émetteur par Industrie Canada. Dans le but de réduire les risques de brouillage radioélectrique à l’intention des autres utilisateurs, il faut choisir le type d’antenne et son gain de sorte que la puissance isotope rayonnée équivalente (p.i.r.e.) ne dépasse pas l'intensité nécessaire à l'établissement d'une communication satisfaisante.

Part 2: This radio transmitter (LOBSRF-305) has been approved by Industry Canada to operate with the antenna type listed below with the maximum permissible gain and required antenna impedance for each antenna type indicated. Antenna types not included in this list, having a gain greater than the maximum gain indicated for that type, are strictly prohibited for use with this device.

Partie 2 : Le présent émetteur radio (LOBSRF-305) a été approuvé par Industrie Canada pour fonctionner avec les types d’antenne énumérés ci-dessous et ayant un gain admissible maximal et l’impédance requise pour chaque type d’antenne. Les types d’antenne non inclus dans cette liste, au dont le gain est supérieur au gain maximal indiqué, sont strictement interdits pour l’exploitation de l’émetteur.

This document is the property of Cervis, Inc. and cannot be copied, modified, e-mailed, or reproduced without the express prior written consent of Cervis, Inc.

Cervis, Inc. reserves the right to change this manual or edit, delete, or modify any information without prior notification.
Table of Contents

FCC Statements .......................................................................................................................... ii
Table of Contents........................................................................................................................ i
List of Figures ............................................................................................................................... ii
List of Tables ............................................................................................................................... ii
Cervis, Inc. Safety Precautions ................................................................................................. iv
1.0  SmaRT BU-xH6R Base Unit ............................................................................................... 1
  1.1  Base Unit Installation ......................................................................................................... 3
  1.2  Optional Antenna Extension Installation ....................................................................... 5
  1.3  BU-xH6R Wiring ............................................................................................................... 6
  1.4  External Protection Devices for Relay Contacts .............................................................. 7
  1.5  Standard Configuration Output Check/Operating Mode Interlock ................................ 7
2.0  SmaRT BU-xH6R Specifications ....................................................................................... 9
3.0  SmaRT BU-xH6R Variations ............................................................................................... 10
4.0  BU-xH6R Troubleshooting Hints .................................................................................... 12
5.0  BU-xH6R (BU-xH6R-EXT) Antenna and Cable List ....................................................... 14
Appendix A: Exposure to Radio Frequency Energy .............................................................. 15
Appendix B: Agency Identification Label Locations .............................................................. 15
Appendix C: Typical Handheld to Base Unit Communication ............................................. 15
  C1: BU-xH6R/PTO Remote Communication ...................................................................... 16
  C2: BU-xH6R/CB Remote Communication ......................................................................... 18
  C3: BU-xH6R/MCB Remote Communication ..................................................................... 20
  C4: BU-xH6R/PG Remote Communication ......................................................................... 22
  C5: BU-xH6R/XX-218 Remote Communication ................................................................. 23

©2020 Cervis, Inc.
List of Figures

Figure 1. BU-xH6R LEDs .................................................................1
Figure 2. Mounting Holes and Cable Connectors P1 and P2 ..................3
Figure 3. 2.4GHz and 900MHz External Antenna Mounting Dimensions ......4
Figure 4. Antenna Extension Kit Installation ....................................5
Figure 5. Dual Connectors/Pin Numbers (enhanced) ............................6
Figure 6. P1 and P2 Field Wiring Layout .........................................6
Figure 7. Typical MOV and Suggested MOV Wiring Across the Contactor Coils ......7
Figure 8. Agency Identification Label Locations ................................15
Figure 9. Associate/Dissociate Buttons ..........................................16
Figure 10. Associate and Dissociate Switch Actuations .....................18
Figure 11. MCB Switch Actuation for Associate and Dissociate ............21
Figure 12. PG Switch Actuation for Associate and Dissociate ..............22
Figure 13. XX-218 Associate Mode .................................................23
Figure 14. XX-218 Dissociate Mode .................................................24

List of Tables

Table 1. Power and Communication Options and Pins References ......................6
Table 2. Base Unit Output LED Interlock Indications ..........................7
Table 3. SmaRT BU-xH6R Specifications ..........................................9
Table 4. SmaRT BU-xH6R Variations ..............................................10
Table 5. BU-xH6R Troubleshooting Hints .......................................12
Table 6. Compatible BU-xH6R (BU-xH6R-EXT) External Antenna Details ....14
Table 7. Compatible BU-xH6R P1 and P2 Cables ..................................14
Definitions/Notes

**Associate**
SmaRT configuration method using a series of specific remote unit button presses to establish a communication link between a SmaRT handheld and a SmaRT base unit.

**CAN**
Controller Area Network: a standard high-speed serial network interface used in a variety of industrial and vehicular applications.

**DSSS**
Direct Sequence Spread Spectrum; an advanced wireless communication technology.

**Disassociate/Dissociate**
Dissolution of all established communication links between handholds and a base unit.

**IP65**
IEC (International Electrotechnical Commission) rating that classifies the level of protection that an enclosure provides.
IP (international protection)
6 (dust tight)
5 (water jetted from any direction on the enclosure shall have no harmful effects)

**PTO**
Push to Operate: Command broadcast only while a button is depressed. The command ends when the button is released.

**BU-xH6R**
Base unit with six relay outputs controlled by a SmaRT handheld remote. Each SmaRT BU-xH6R can communicate with up to eight handhelds.

**SmaRT 9nn or 2nn Remote Control System**
SmaRT system consisting of one SmaRT base unit and from one to eight SmaRT remote control units. The system operates in the 900 MHz range (9nn) or 2.4 GHz (2nn) and has some defined number (nn) of outputs.
For instance, a SmaRT 904 Remote Control System operates in the 900 MHz range, and the remote can control a maximum of four outputs.

**Line of Sight (aka Direct-Line-of-Sight)**
Type of communication between transceivers—or a transmitter and a receiver—where the pathway between the two units must be clear of obstacles.

**TX/RX**
Transmit/Receive

**MOV (Metal Oxide Varister)**
Discrete electronic component commonly used to divert excessive current. A protection device used to suppress noise that can have an undesired effect on equipment and systems.

**Snubber (Snubber Circuit)**
Electrical circuit used to suppress electrical spikes (transients) by diverting excess current around the protected device.

**RS-232**
Low-speed serial interface used for base unit configuration.
Cervis, Inc. Safety Precautions

✓ Read and follow all instructions.
✓ Failure to abide by Safety Precautions may cause equipment failure, loss of authority to operate the equipment, and personal injury.
✓ Use and maintain proper wiring. Follow equipment manufacturer instructions. Improper, loose, and frayed wiring can cause system failure, equipment damage, and intermittent operation.
✓ Changes or modifications made to equipment not expressly approved by the manufacturer will void the warranty.
✓ Equipment owner/operators must abide by all applicable Federal, State, and Local laws concerning equipment installation and operation. Failure to comply could result in penalties and could void user authority to operate the equipment.
✓ Make sure that the machinery and surrounding area is clear before operating. Do not activate the remote control system until certain that it is safe to do so.
✓ Remove power from the base unit before attempting any maintenance. This will prevent accidental operation of the controlled machinery.
✓ Remove power from the base unit by detaching the 12-pin cables from the base unit connectors P1 and P2, or by removing the source power from the circuit.
✓ Use a damp cloth to keep units clean. Remove mud, concrete, dirt, etc. after use to prevent obstructing or clogging the wiring and switches.
✓ Do not allow liquid to enter the base unit enclosures. Do not use high-pressure equipment to clean the base unit.
✓ Disconnect the base unit before welding on the machine. Failure to disconnect the base unit may cause destruction of or damage to the base unit.
✓ Operate and store units only within the specified operation and storage temperatures defined in this document’s specifications.
1.0 SmaRT BU-xH6R Base Unit

The SmaRT BU-xH6R Base Unit features six Form C relay outputs. Each Form C relay contact can switch up to 8 amperes at 250 VAC or VDC. Using Direct Sequence Spread Spectrum (DSSS) wireless technology at 900 MHz or 2.4 GHz, the base unit robustly links with a handheld remote control unit in congested radio environments at extended ranges. All controlled apparatus connections—and base unit power—are made using two cables with keyed, heavy duty 12-pin connectors, through which output signals are also ported. Five status/diagnostic LEDs shown in Figure 1 below determine the state of the unit.

![Figure 1. BU-xH6R LEDs](image)

**BU-xH6R Input Power**

Input power depends on the type of BU-xH6R used:

- **BU-xH6R-xxx-HVU** accepts input voltage of 100–240 VAC @ 47–440 Hz, or 120–370 VDC. The –HVU power option uses a universal converter that can accept either high-voltage AC or DC input. The converter is not polarity sensitive.

- **BU-xH6R-xxx-LVD** accepts 7–32 VDC. The –LVD option is polarity sensitive to:
  - Enhance low input voltage behavior.
  - Prevent resets—due to sagging battery voltage when an engine is started—from occurring.

- **BU-xH6R-xxx-LVA** accepts 7–28 VAC, 50/60 Hz. The –LVA option permits operation using readily available step-down control voltage transformers for power.

An optional Controller Area Network (CAN) interface feature is available for networking multiple base units in more complex control applications. Contact Cervis, Inc. for more information.

An RS-232 interface is available for use with SmaRT Connect. Due to pin limitations, it is not available if the CAN option is selected.

©2020 Cervis, Inc.
BU-xH6R Base Unit Features

(See Table 4 for a complete listing.)

- Capable of communicating to up to eight SmaRT handheld remote control units
- License-free frequency, Direct Sequence Spread Spectrum (DSSS) technology for 900 MHz @ 10mW or 2.4 GHz @ 100 mW radio frequency (RF) power
- CAN interface optional
- Internal antenna standard; external antenna optional
- 300 m (1000 ft.) range*
- Six independent relay outputs, each with a single Form C contact
- 8A maximum switching per contact at 250 VAC or VDC
- Rugged, compact high-impact polymer, weatherproof IP65 enclosure design
- Three available input voltage platforms
- Five viewable external diagnostic LEDs
- RS-232 interface for SmaRT Connect configuration

*with external antenna
1.1 Base Unit Installation

**Caution**

During installation, make sure the machine that the base unit will be attached to is disabled.

Use the configuration diagrams supplied by Cervis, Inc. to guide you in mounting the base unit and connecting your wiring harness cables. Base unit mounting is left much to your discretion with the following guidelines:

- Before installing, make sure that the configuration diagrams supplied with the system are available. Keep them where they are available at all times.
- Make sure the wiring harness cables are on hand.
- Always mount the receiver away from any intense radio or electric disturbance sources.
- Make sure the mount is secure. Mount the unit where you have enough room for your wiring harness connections.
- If exposed to rain or low-pressure water jets, Cervis, Inc. recommends installing the base unit as shown, with the connectors down. Plus, a drip-loop formed with the cables is a good-practice recommendation.

**Caution**

The base unit enclosure and connectors are NOT rated for high-pressure washing. Doing so could damage the base unit or connectors.

*Figure 2. Mounting Holes and Cable Connectors P1 and P2*
Figure 3. 2.4 GHz and 900 MHz External Antenna Mounting Dimensions
1.2 Optional Antenna Extension Installation

Both the 10-ft. and 3-ft. antenna extension cables are compatible with 2.4 GHz and 900 MHz antennas. The antenna example shown in Figure 4 is a 2.4 GHz antenna.

Make sure the antenna is located in clear line-of-sight of the remote.

1. Loosen and remove extension cable nut to allow the antenna ferrule to push through a mounting hole (user discretion).
2. Rethread the nut to secure the ferrule to the device.
3. Attach cable extension to the BU-xH6R.
4. Attach the antenna to the extension ferrule.

Figure 4. Antenna Extension Kit Installation
1.3 BU-xH6R Wiring

Figure 5. Dual Connectors/Pin Numbers (enhanced)

If the base unit supply voltage drops below a minimum volt level—even momentarily—the unit will reset. Minimum supply voltages are:

- 7 VDC for a BU-xH6R-xxx-LVD
- 7 VAC for a BU-xH6R-xxx-LVA
- 90 VAC or 100 VDC for a BU-xH6R-xxx-HVU

Caution

If the supply voltage drops below minimum input volts for a consistent period of time, the LEDs (including the TX/RX LEDs, if transceiving) will dim and flicker. These circumstances are symptoms of a battery or power source that cannot sustain the present current load. Remedy this situation as soon as possible.

Figure 6. P1 and P2 Field Wiring Layout

Table 1. Power and Communication Options and Pins References

<table>
<thead>
<tr>
<th>Communication Options</th>
<th>P1 Pins</th>
<th>Power Options</th>
<th>V_{in}</th>
<th>P2 Pins</th>
</tr>
</thead>
<tbody>
<tr>
<td>RS-232 TX / CAN H</td>
<td>4</td>
<td>–HVU</td>
<td>100–240 VAC</td>
<td>7, 9</td>
</tr>
<tr>
<td>RS-232 RX / CAN L</td>
<td>5</td>
<td>–LVA</td>
<td>7–28 VAC</td>
<td>7, 8</td>
</tr>
<tr>
<td></td>
<td></td>
<td>–LVD</td>
<td>7–32 VDC</td>
<td>7(-), 8(+)</td>
</tr>
</tbody>
</table>
1.4 External Protection Devices for Relay Contacts

Depending on the model, the BU-xH6R may have internal snubbing circuits to protect the relay contacts. (See Table 4, AC Sup.) Each snubber consists of a 47 Ω resistor in series with a 0.1 μF capacitor across each relay contact. However, the internal snubbers may not be adequate for all loads and applications. An MOV—or Metal Oxide Varistor—is a protection device used to suppress high-transient voltages that can cause relay contact deterioration, especially when switching inductive loads such as solenoids or relay coils. They protect circuits against excessive transient voltages by clamping the voltage to a safe level and dissipating the unwanted energy. To provide proper protection, the MOV must have a voltage rating and an energy dissipation rating appropriate to the application. Other devices—such as power Zener diodes or R-C snubbers—may be necessary, depending on the application and whether the switched circuits are AC or DC.

When using contactors or solenoids with SmaRT systems, Cervis, Inc. advises using external protective devices by connecting them across the coils as shown in the examples below using MOVs.

![Figure 7. Typical MOV and Suggested MOV Wiring Across the Contactor Coils](image)

In some applications, internal snubbers may not be desired. (See Table 4, AC Sup.) The –NOS option can be specified to omit them. However, this can leave the contacts vulnerable to switching transients and arcing. Contact Cervis, Inc. Customer Service for assistance in choosing appropriate contact protection.

1.5 Standard Configuration

Output Check/Operating Mode Interlock

In the default output configuration, there is an interlock that prevents an output from activating if an adjacent handheld button is pressed at the same time as the intended button. Once the remote is associated to the base unit (see Appendix C), outputs—when properly wired—respond and are indicated by the base unit OUT (output) LED as listed in Table 2.

<table>
<thead>
<tr>
<th>Handheld Remote Momentary Action</th>
<th>Command</th>
<th>BU-xH6R Result</th>
</tr>
</thead>
<tbody>
<tr>
<td>Press and hold function</td>
<td>Activate Output K1</td>
<td>Output K1 active; Output LED lights and remains lit until the PTO Output 1 is released.</td>
</tr>
<tr>
<td>corresponding to Output 1</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Press and hold function</td>
<td>Activate Output K2</td>
<td>Output K2 active; Output LED lights and remains lit until the PTO Output 2 is released.</td>
</tr>
<tr>
<td>corresponding to Output 2</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Press and hold function</td>
<td>Operating Mode Interlock</td>
<td>Operating Mode Interlock prevents K1 and K2 output activity. Output LED is unlit.</td>
</tr>
<tr>
<td>corresponding to Output 1 and</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Output 2</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Press and hold function</td>
<td>Activate Output K3</td>
<td>Output K3 active; Output LED lights and remains lit until the PTO Output 3 is released.</td>
</tr>
<tr>
<td>corresponding to Output 3</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Press and hold function</td>
<td>Activate Output K4</td>
<td>Output K4 active; Output LED lights and remains lit until the PTO Output 4 is released.</td>
</tr>
<tr>
<td>corresponding to Output 4</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Handheld Remote Momentary Action</td>
<td>Command</td>
<td>BU-xH6R Result</td>
</tr>
<tr>
<td>---------------------------------------------------------------------</td>
<td>--------------------</td>
<td>-------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>Press and hold function corresponding Output 3 and Output 4</td>
<td>Operating Mode Interlock</td>
<td>Operating Mode Interlock prevents K3 and K4 output activity. Output LED is unlit.</td>
</tr>
<tr>
<td>Press and hold function corresponding Output 5</td>
<td>Activate Output K5</td>
<td>Output K5 active; Output LED lights and remains lit until the PTO Output 5 is released.</td>
</tr>
<tr>
<td>Press and hold function corresponding Output 6</td>
<td>Activate Output K6</td>
<td>Output K6 active; Output LED lights and remains lit until the PTO Output 6 is released.</td>
</tr>
<tr>
<td>Press and hold function corresponding Output 5 and Output 6</td>
<td>Operating Mode Interlock</td>
<td>Operating Mode Interlock prevents K5 and K6 output activity. Output LED is unlit.</td>
</tr>
</tbody>
</table>

✓ Note: The default configuration can be modified to suit the needs of the application if necessary.
## 2.0 SmaRT BU-xH6R Specifications

### Table 3. SmaRT BU-xH6R Specifications

<table>
<thead>
<tr>
<th>Item</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Power</strong></td>
<td></td>
</tr>
<tr>
<td>Operating Power</td>
<td>5 W max.</td>
</tr>
<tr>
<td>RF power</td>
<td>10 mW @ 900 MHz; 100 mW @ 2.4 GHz</td>
</tr>
<tr>
<td><strong>Vin</strong></td>
<td></td>
</tr>
<tr>
<td>BU-xH6R-xxx-HVU</td>
<td>100–240 VAC @ 47–440 Hz, or 120–370 VDC</td>
</tr>
<tr>
<td>BU-xH6R-xxx-LVD</td>
<td>7–32 VDC</td>
</tr>
<tr>
<td>BU-xH6R-xxx-LVA</td>
<td>7–28 VAC</td>
</tr>
<tr>
<td><strong>Environment</strong></td>
<td></td>
</tr>
<tr>
<td>Operating temp.</td>
<td>–25° C to 60° C (–13° F to 140° F)</td>
</tr>
<tr>
<td>Storage temp.</td>
<td>–40° C to 85° C (–40° F to 185° F)</td>
</tr>
<tr>
<td>Humidity</td>
<td>0 to 100%</td>
</tr>
<tr>
<td>Vibration/Shock</td>
<td>IEC60068-2-6 10 Hz to 150 Hz @ 1.0 g peak acceleration 10.0 g peak shock acceleration</td>
</tr>
<tr>
<td><strong>Radio</strong></td>
<td></td>
</tr>
<tr>
<td>Frequency</td>
<td>906–924 MHz; 2405–2480 MHz</td>
</tr>
<tr>
<td>License</td>
<td>No license required</td>
</tr>
<tr>
<td>Modulation</td>
<td>Channel-Hopping DSSS</td>
</tr>
<tr>
<td>Antenna</td>
<td>Internal</td>
</tr>
<tr>
<td><strong>Enclosure</strong></td>
<td></td>
</tr>
<tr>
<td>Dimensions</td>
<td>mm: 133 x 118 x 36; inch: 5.24 x 4.65 x 1.42</td>
</tr>
<tr>
<td>Weight</td>
<td>340 g; 0.75 lbs.</td>
</tr>
<tr>
<td>Durability</td>
<td>High Impact Polymer</td>
</tr>
<tr>
<td><strong>Indicators</strong></td>
<td></td>
</tr>
<tr>
<td>CAN TX/RX</td>
<td>Red CAN active transmit</td>
</tr>
<tr>
<td></td>
<td>Green CAN active receive</td>
</tr>
<tr>
<td>Out</td>
<td>Lit Active output</td>
</tr>
<tr>
<td>Health</td>
<td>Green Pulse/Sec. OK</td>
</tr>
<tr>
<td>TX/RX</td>
<td>Green Receive</td>
</tr>
<tr>
<td>Power</td>
<td>Red Transmit</td>
</tr>
<tr>
<td></td>
<td>Amber OK</td>
</tr>
<tr>
<td></td>
<td>Red/Green Fault</td>
</tr>
<tr>
<td><strong>Outputs</strong></td>
<td></td>
</tr>
<tr>
<td>Contacts</td>
<td>Six Form C</td>
</tr>
<tr>
<td></td>
<td>Each rated 8 A max. switching @ 250 VAC or VDC: 100 mA min. @ 5 VDC.</td>
</tr>
<tr>
<td></td>
<td>48 A max. total output</td>
</tr>
<tr>
<td><strong>CAN Option</strong></td>
<td>Protocol SAE J1939</td>
</tr>
<tr>
<td><strong>RS-232</strong></td>
<td>Settings 19,200 bits/sec, N, 8, 1 (Not available with CAN option.)</td>
</tr>
</tbody>
</table>
### 3.0 SmaRT BU-xH6R Variations

**Common Features:**

No Display; Channel Type are all Form C Relays; Number of channels each is 6.

---

**Table 4. SmaRT BU-xH6R Variations**

<table>
<thead>
<tr>
<th>Model</th>
<th>Freq</th>
<th>RF Pwr</th>
<th>Input Pwr</th>
<th>Antenna</th>
<th>Serial Port</th>
<th>AC sup</th>
<th>SmaRT Connect</th>
</tr>
</thead>
<tbody>
<tr>
<td>BU-9H6R-INT-LVD</td>
<td>900 MHz</td>
<td>10 mW</td>
<td>7–32 VDC</td>
<td>Internal</td>
<td>RS-232</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>BU-9H6R-INT-LVD-CAN</td>
<td>900 MHz</td>
<td>10 mW</td>
<td>7–32 VDC</td>
<td>Internal</td>
<td>CAN</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>BU-9H6R-INT-LVD-NOS</td>
<td>900 MHz</td>
<td>10 mW</td>
<td>7–32 VDC</td>
<td>Internal</td>
<td>CAN</td>
<td>No</td>
<td>Yes</td>
</tr>
<tr>
<td>BU-9H6R-INT-LVD-NOS-CAN</td>
<td>900 MHz</td>
<td>10 mW</td>
<td>7–32 VDC</td>
<td>Internal</td>
<td>CAN</td>
<td>No</td>
<td>No</td>
</tr>
<tr>
<td>BU-9H6R-INT-LVA</td>
<td>900 MHz</td>
<td>10 mW</td>
<td>7–28 VAC</td>
<td>Internal</td>
<td>RS-232</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>BU-9H6R-INT-LVA-CAN</td>
<td>900 MHz</td>
<td>10 mW</td>
<td>7–28 VAC</td>
<td>Internal</td>
<td>CAN</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>BU-9H6R-INT-LVA-NOS</td>
<td>900 MHz</td>
<td>10 mW</td>
<td>7–28 VAC</td>
<td>Internal</td>
<td>CAN</td>
<td>No</td>
<td>No</td>
</tr>
<tr>
<td>BU-9H6R-INT-LVA-NOS-CAN</td>
<td>900 MHz</td>
<td>10 mW</td>
<td>7–28 VAC</td>
<td>Internal</td>
<td>CAN</td>
<td>No</td>
<td>No</td>
</tr>
<tr>
<td>BU-9H6R-INT-HVU</td>
<td>900 MHz</td>
<td>10 mW</td>
<td>100–240 VAC</td>
<td>Internal</td>
<td>CAN</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>BU-9H6R-INT-HVU-CAN</td>
<td>900 MHz</td>
<td>10 mW</td>
<td>100–240 VAC</td>
<td>Internal</td>
<td>CAN</td>
<td>No</td>
<td>No</td>
</tr>
<tr>
<td>BU-9H6R-INT-HVU-NOS</td>
<td>900 MHz</td>
<td>10 mW</td>
<td>100–240 VAC</td>
<td>Internal</td>
<td>CAN</td>
<td>No</td>
<td>No</td>
</tr>
<tr>
<td>BU-9H6R-INT-HVU-NOS-CAN</td>
<td>900 MHz</td>
<td>10 mW</td>
<td>100–240 VAC</td>
<td>Internal</td>
<td>CAN</td>
<td>No</td>
<td>No</td>
</tr>
<tr>
<td>BU-9H6R-EXT-LVD</td>
<td>900 MHz</td>
<td>10 mW</td>
<td>7–32 VDC</td>
<td>External</td>
<td>RS-232</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>BU-9H6R-EXT-LVD-CAN</td>
<td>900 MHz</td>
<td>10 mW</td>
<td>7–32 VDC</td>
<td>External</td>
<td>CAN</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>BU-9H6R-EXT-LVD-NOS</td>
<td>900 MHz</td>
<td>10 mW</td>
<td>7–32 VDC</td>
<td>External</td>
<td>CAN</td>
<td>No</td>
<td>Yes</td>
</tr>
<tr>
<td>BU-9H6R-EXT-LVD-NOS-CAN</td>
<td>900 MHz</td>
<td>10 mW</td>
<td>7–32 VDC</td>
<td>External</td>
<td>CAN</td>
<td>No</td>
<td>Yes</td>
</tr>
<tr>
<td>BU-9H6R-EXT-LVA</td>
<td>900 MHz</td>
<td>10 mW</td>
<td>7–28 VAC</td>
<td>External</td>
<td>RS-232</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>BU-9H6R-EXT-LVA-CAN</td>
<td>900 MHz</td>
<td>10 mW</td>
<td>7–28 VAC</td>
<td>External</td>
<td>CAN</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>BU-9H6R-EXT-LVA-NOS</td>
<td>900 MHz</td>
<td>10 mW</td>
<td>7–28 VAC</td>
<td>External</td>
<td>CAN</td>
<td>No</td>
<td>No</td>
</tr>
<tr>
<td>BU-9H6R-EXT-LVA-NOS-CAN</td>
<td>900 MHz</td>
<td>10 mW</td>
<td>7–28 VAC</td>
<td>External</td>
<td>CAN</td>
<td>No</td>
<td>No</td>
</tr>
<tr>
<td>BU-9H6R-EXT-HVU</td>
<td>900 MHz</td>
<td>10 mW</td>
<td>100–240 VAC</td>
<td>External</td>
<td>CAN</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>BU-9H6R-EXT-HVU-CAN</td>
<td>900 MHz</td>
<td>10 mW</td>
<td>100–240 VAC</td>
<td>External</td>
<td>CAN</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>BU-9H6R-EXT-HVU-NOS</td>
<td>900 MHz</td>
<td>10 mW</td>
<td>100–240 VAC</td>
<td>External</td>
<td>CAN</td>
<td>No</td>
<td>No</td>
</tr>
<tr>
<td>BU-9H6R-EXT-HVU-NOS-CAN</td>
<td>900 MHz</td>
<td>10 mW</td>
<td>100–240 VAC</td>
<td>External</td>
<td>CAN</td>
<td>No</td>
<td>No</td>
</tr>
<tr>
<td>BU-2H6R-INT-LVD</td>
<td>2.4 GHz</td>
<td>100 mW</td>
<td>7–32 VDC</td>
<td>Internal</td>
<td>RS-232</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>BU-2H6R-INT-LVD-CAN</td>
<td>2.4 GHz</td>
<td>100 mW</td>
<td>7–32 VDC</td>
<td>Internal</td>
<td>CAN</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>BU-2H6R-INT-LVD-NOS</td>
<td>2.4 GHz</td>
<td>100 mW</td>
<td>7–32 VDC</td>
<td>Internal</td>
<td>CAN</td>
<td>No</td>
<td>Yes</td>
</tr>
<tr>
<td>BU-2H6R-INT-LVD-NOS-CAN</td>
<td>2.4 GHz</td>
<td>100 mW</td>
<td>7–32 VDC</td>
<td>Internal</td>
<td>CAN</td>
<td>No</td>
<td>Yes</td>
</tr>
<tr>
<td>BU-2H6R-INT-LVA</td>
<td>2.4 GHz</td>
<td>100 mW</td>
<td>7–28 VAC</td>
<td>Internal</td>
<td>RS-232</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>BU-2H6R-INT-LVA-CAN</td>
<td>2.4 GHz</td>
<td>100 mW</td>
<td>7–28 VAC</td>
<td>Internal</td>
<td>CAN</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>BU-2H6R-INT-HVU</td>
<td>2.4 GHz</td>
<td>100 mW</td>
<td>100–240 VAC</td>
<td>Internal</td>
<td>RS-232</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>BU-2H6R-INT-HVU-CAN</td>
<td>2.4 GHz</td>
<td>100 mW</td>
<td>100–240 VAC</td>
<td>Internal</td>
<td>CAN</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>BU-2H6R-INT-HVU-NOS</td>
<td>2.4 GHz</td>
<td>100 mW</td>
<td>100–240 VAC</td>
<td>Internal</td>
<td>CAN</td>
<td>No</td>
<td>No</td>
</tr>
<tr>
<td>BU-2H6R-INT-HVU-NOS-CAN</td>
<td>2.4 GHz</td>
<td>100 mW</td>
<td>100–240 VAC</td>
<td>Internal</td>
<td>CAN</td>
<td>No</td>
<td>No</td>
</tr>
<tr>
<td>BU-2H6R-EXT-LVD</td>
<td>2.4 GHz</td>
<td>100 mW</td>
<td>7–32 VDC</td>
<td>External</td>
<td>RS-232</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>BU-2H6R-EXT-LVD-CAN</td>
<td>2.4 GHz</td>
<td>100 mW</td>
<td>7–32 VDC</td>
<td>External</td>
<td>CAN</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>BU-2H6R-EXT-LVD-NOS</td>
<td>2.4 GHz</td>
<td>100 mW</td>
<td>7–32 VDC</td>
<td>External</td>
<td>CAN</td>
<td>No</td>
<td>Yes</td>
</tr>
<tr>
<td>BU-2H6R-EXT-LVD-NOS-CAN</td>
<td>2.4 GHz</td>
<td>100 mW</td>
<td>7–32 VDC</td>
<td>External</td>
<td>CAN</td>
<td>No</td>
<td>Yes</td>
</tr>
<tr>
<td>BU-2H6R-EXT-LVA</td>
<td>2.4 GHz</td>
<td>100 mW</td>
<td>7–28 VAC</td>
<td>External</td>
<td>RS-232</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>BU-2H6R-EXT-LVA-CAN</td>
<td>2.4 GHz</td>
<td>100 mW</td>
<td>7–28 VAC</td>
<td>External</td>
<td>CAN</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>BU-2H6R-EXT-LVA-NOS</td>
<td>2.4 GHz</td>
<td>100 mW</td>
<td>7–28 VAC</td>
<td>External</td>
<td>CAN</td>
<td>No</td>
<td>No</td>
</tr>
<tr>
<td>BU-2H6R-EXT-LVA-NOS-CAN</td>
<td>2.4 GHz</td>
<td>100 mW</td>
<td>7–28 VAC</td>
<td>External</td>
<td>CAN</td>
<td>No</td>
<td>No</td>
</tr>
<tr>
<td>Model</td>
<td>Freq</td>
<td>RF Pwr</td>
<td>Input Pwr</td>
<td>Antenna</td>
<td>Serial Port</td>
<td>AC sup</td>
<td>SmarRT Connect</td>
</tr>
<tr>
<td>-----------------------------</td>
<td>----------</td>
<td>--------</td>
<td>-----------</td>
<td>---------</td>
<td>-------------</td>
<td>--------</td>
<td>----------------</td>
</tr>
<tr>
<td>BU-2H6R-EXT-LVA-NOS-CAN</td>
<td>2.4 GHz</td>
<td>100 mW</td>
<td>7–28 VAC</td>
<td>External</td>
<td>CAN</td>
<td>No</td>
<td>No</td>
</tr>
<tr>
<td>BU-2H6R-EXT-HVU</td>
<td>2.4 GHz</td>
<td>100 mW</td>
<td>100–240 VAC</td>
<td>External</td>
<td>RS-232</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>BU-2H6R-EXT-HVU-CAN</td>
<td>2.4 GHz</td>
<td>100 mW</td>
<td>100–240 VAC</td>
<td>External</td>
<td>CAN</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>BU-2H6R-EXT-HVU-NOS</td>
<td>2.4 GHz</td>
<td>100 mW</td>
<td>100–240 VAC</td>
<td>External</td>
<td>RS-232</td>
<td>No</td>
<td>Yes</td>
</tr>
<tr>
<td>BU-2H6R-EXT-HVU-NOS-CAN</td>
<td>2.4 GHz</td>
<td>100 mW</td>
<td>100–240 VAC</td>
<td>External</td>
<td>CAN</td>
<td>No</td>
<td>No</td>
</tr>
</tbody>
</table>
## 4.0 BU-xH6R Troubleshooting Hints

**Table 5. BU-xH6R Troubleshooting Hints**

<table>
<thead>
<tr>
<th>Indication</th>
<th>Cause</th>
<th>Solution†</th>
</tr>
</thead>
<tbody>
<tr>
<td>Power (LED 5)</td>
<td></td>
<td>✓ Is +VDC input power present?</td>
</tr>
</tbody>
</table>
| RF TX/RX (LED 4) not active | Electrical signals not activating the LEDs. | ✓ Check for obstructions preventing line-of-sight transmission.  
|                             |                                            | ✓ Check that the remote control unit is active.         |
|                             |                                            | ✓ Re-associate the remote control unit with the base unit. |
| CAN TX/RX (LED 1) not active|                                            | ✓ Check CAN wiring.                                    |
|                             |                                            | ✓ Check that the remote control unit is active.         |
|                             |                                            | ✓ Re-associate the remote control unit to the base unit. |
| Out LED (LED 2) not active  |                                            | ✓ Check that the remote control unit LEDs are active when the appropriate buttons are pushed. |
|                             |                                            | ✓ Check that the startup sequence was followed.         |
| Health LED (LED 3) blinking rapidly | Indicates an internal problem.           | ✓ Contact Cervis, Inc. service department.               |

† – If the recommended solutions do not resolve the issue, contact the Cervis, Inc. service department.
Push-To-Operate (PTO) means that the outputs under control should only change states when the appropriate handheld button is pressed, and then only for the duration of time that particular output button is pressed. Investigate any unexpected motion that occurs when pressing the handheld output control buttons.

Should a jerkiness of motion occur while constantly pressing an output button, immediately stop operation. Check the OUT LED and the other BU-xH6R diagnostic LEDs for any indication of a problem.

Be aware that even if the handheld and base unit diagnostic LEDs do not indicate a problem, one may be present and further troubleshooting steps may be needed.

If a problem is found, do not operate the SmaRT System until the problem is resolved.
5.0 BU-xH6R (BU-xH6R-EXT) Antenna and Cable List

Table 6. Compatible BU-xH6R (BU-xH6R-EXT) External Antenna Details

<table>
<thead>
<tr>
<th>Part</th>
<th>Cervis BIN</th>
</tr>
</thead>
<tbody>
<tr>
<td>900 MHz IS BAND swivel antenna</td>
<td>BB3-06</td>
</tr>
<tr>
<td>2.4 GHz swivel antenna, +3 dBi</td>
<td>BB3-07</td>
</tr>
<tr>
<td>3 ft. antenna extension cable</td>
<td>J5-02</td>
</tr>
<tr>
<td>10 ft. antenna extension cable</td>
<td>J5-02</td>
</tr>
<tr>
<td>10 ft. antenna cable (J5-02) and external antenna (BB3-06)</td>
<td>EXT-10-900</td>
</tr>
<tr>
<td>3 ft. antenna cable (J5-07) and external antenna (BB3-06)</td>
<td>EXT-3-900</td>
</tr>
</tbody>
</table>

✓ Note: Only use the antenna recommended by Cervis, Inc. with the SmaRT base unit.

Table 7. Compatible BU-xH6R P1 and P2 Cables

<table>
<thead>
<tr>
<th>Wiring Harness</th>
<th>Part Number</th>
</tr>
</thead>
<tbody>
<tr>
<td>Cable P1</td>
<td>HN-1003 (for P1)</td>
</tr>
<tr>
<td>Cable P2</td>
<td>HN-1004 (for P2)</td>
</tr>
<tr>
<td>Single Cable, Dual Connector</td>
<td>HN-1006 (colored wires)</td>
</tr>
</tbody>
</table>
Appendix A: Exposure to Radio Frequency Energy

SmaRT base units contain radio transceivers. When active, base units send out radio frequency (RF) energy through an internal or external antenna. The SmaRT base unit complies with limits set by the United States Federal Communications Commission (FCC) for operating distance from human tissue.

SmaRT base units with an external antenna should be mounted to ensure that the antenna is at least 20 cm away from the human body. Only use the external antennas recommended by Cervis, Inc. (see Table 6).

Appendix B: Agency Identification Label Locations

![Agency Identification Label Locations](image)

Note: Individual SmaRT base unit models use the illustrated label position for all base unit agency labels. The base unit label position is identical for both internal and external antenna base units.

Appendix C: Typical Handheld to Base Unit Communication

A standard SmaRT System consists of one handheld remote and one base unit. Each base unit can communicate with up to eight handheld remotes. Each handheld must first establish a communications link with the base unit before the base unit will recognize the handheld unit. This process is called “Association.”

Handheld remote and base unit communications are established at Cervis, Inc. before shipping when systems are ordered. However, it may be necessary to establish or re-establish communication between a remote and a base unit at some point. The Associate procedure does this.

In some cases, it may also become necessary to break the communication link between the handheld and the BU-xH6R. This process is called “Dissociation.” Be aware that when a handheld is dissociated from a base unit, all communication links to that particular base unit are erased from the base unit memory! For instance, a particular BU-xH6R is associated to Handheld Remotes 1 through 5. Remote 2 dissociates—breaks the communication link—from the base unit. Hence, all five handheld remotes are removed from the base unit memory. Any remaining handheld that now needs to control that BU-xH6R must re-establish the communication link using the Associate procedure.

The following Associate and Dissociate procedures are general methods for associating or dissociating Cervis, Inc. handheld remotes to the BU-xH6R. Custom systems may have different Associate methods unique to the custom system design.
C1: BU-xH6R/PTO Remote Communication

To Associate

Before attempting to associate, the base unit and handheld must be OFF. Base unit and SmaRT 2-, 4-, and 6-button handheld association is established using the following steps:

1. Remove power from the base unit and turn off (time out) the handheld device.
2. Stand near the base unit in unobstructed, clear line-of-sight with the handheld in hand.
3. Simultaneously press and hold the Associate (B1) and Dissociate (B2) buttons. The RX and ER LEDs light.
4. Continue to hold both buttons until the TX and RX LEDs light steady.
5. When the TX and RX LEDs light, release B1 and B2. LEDs ER and BA light.

✓ Note: If you do not immediately (within approximately 2 sec.) press the next button, all LEDs flash, and the Associate procedure is aborted. You must then restart the process from Step 1 to establish the communication link.

6. Immediately press and hold the Associate button (B1). All LEDs light.
7. TX begins to slowly blink. Continue to hold B1.
8. Apply power to the base unit.

The handheld and base unit begin to establish a communication link while you hold the Associate button. Once the process is complete, all LEDs light briefly and then go out.

9. Release the Associate button. The TX and RX LEDs blink rapidly, indicating that the base unit is communicating with that particular handheld remote.

Figure 9. Associate/Dissociate Buttons
To Dissociate

In some circumstances, it may become necessary to dissociate—or break the communication link between—a base unit and a handheld remote.

**Caution**  The following steps will break all previously established handheld remote links. It will be necessary to perform the Association Procedure (above) using each handheld to re-establish communication links with a base unit.

1. Remove power from the base unit.
2. Stand near the base unit in clear line of sight with the handheld in your hand.
3. Press and hold both Associate (B1) and Dissociate (B2; see Figure 9) buttons. The RX and ER LEDs light.
4. Continue to hold both buttons until the TX and RX LEDs light steady.
5. When LEDs TX and RX light, release B1 and B2. LEDs ER and BA light.

   **Note:** If you do not press the next button within the two-second interval, all LEDs flash, and the procedure is aborted. You must restart the process from Step 1 to break the communication link.

6. Press and hold the Dissociate button (B2). (See Figure 9 above.) All LEDs light.
8. Apply power to the base unit while continuing to hold the Dissociate button.

The base unit and all previously linked handhelds begin to Dissociate communication links. Once the process is complete, all LEDs light briefly and then go out.

9. Release the Dissociate button.

The SmarRT base unit will not communicate with any handheld remote units. A handheld remote must use the Association Procedure (above) to re-establish a communication link with the base unit.
C2: BU-xH6R/CB Remote Communication

**Caution**

To prevent inadvertent machine movement, be sure to remove power from the Base Unit before attempting to Associate or Dissociate.

Before starting the Association process, turn OFF the console box remote and remove power from the base unit.

✓ **Note:** The Machine Stop button must be in the UP position before activating and using the console remote.

**To Associate (see Figure 10)**

1. Stand near the base unit with the console remote OFF and power removed from the base unit (detach the P1 and P2 cables from the base unit, or remove the power source.)
2. Twist and pull UP the red Stop button on the remote.
3. Hold the Associate switch (S13) UP. While holding the Associate switch UP, activate the console remote by holding switch S12 UP (ON). Continue to hold both switches.
4. Observe the LEDs. When TX begins to blink, power up the base unit while continuing to hold S13 and S12. When TX, RX, ERR, and BAT light solid, release S13 and S12.

A successful association is indicated when LEDs TX and RX are rapidly blinking in unison.

![Step 3 Associate and Dissociate Switch Actuations](image)

**Figure 10. Associate and Dissociate Switch Actuations**

**To Dissociate (see Figure 10)**

The CB remote must be OFF and the base unit must have power removed before starting the Dissociation process.

✓ **Note:** The Machine Stop button must be in the UP position before activating and using the console remote.

1. Stand near the base unit with the console remote OFF and power removed from the base unit (detach the P1 and P2 cables from the base unit, or remove the power source.)
2. Twist and pull UP the red Stop button on the remote.
3. Hold the Associate switch (S13) DOWN. While holding the Associate switch DOWN, activate the console remote by holding switch S12 UP (ON). Continue to hold both switches.
4. Observe the LEDs. When TX begins to blink, power up the base unit while continuing to hold S13 and S12. When TX, RX, ERR, and BAT light solid, release S13 and S12.
Note: Be aware that all remote associations to the base unit are now broken.
C3: BU-xH6R/MCB Remote Communication

**To prevent inadvertent machine movement, be sure to remove power from the Base Unit before attempting to Associate or Dissociate.**

To Associate (see Figure 11)

*The MCB remote must be OFF and the base unit must have power removed before starting the Association process.*

✓ **Note:** The Machine Stop button must be in the UP position before activating and using the console remote.

1. Stand near the base unit with the remote OFF and power removed from the base unit (disconnect the P1 and P2 cables or turn the source power OFF).
2. Release the STOP button on the MCB handheld by pulling it up.
3. Push and hold switch S1 UP; then press the Power ON button. All four LEDs light solid.
4. Observe the LEDs. When TX begins to blink, power up the base unit while continuing to hold switch S1 and the Power button. When all four LEDs light solid, release switch S1 and the Power Button.

A successful Association is indicated when LEDs TX and RX are rapidly blinking in unison.
To Dissociate (see Figure 11)

The MCB remote must be OFF and the base unit must have power removed before the Dissociation process can be started.

✓ Note: The Machine Stop button must be in the UP position before activating and using the console remote.

1. Stand near the base unit with the remote OFF and power removed from the base unit (disconnect the P1 and P2 cables or turn the source power OFF).
2. Release the STOP button on the MCB handheld by pulling it up.
3. Push and hold switch S1 DOWN; then press the Power ON button. All four LEDs light solid.
4. Observe the LEDs. When TX begins to blink, power up the base unit while continuing to hold switch S1 and the Power button. When all four LEDs light solid, release S1 and the pushbutton.

✓ Note: Be aware that all remote associations to the base unit are now broken.
C4: BU-xH6R/PG Remote Communication

To Associate (See Figure 12).
The PG remote must be OFF, and the base unit must have power removed before starting the Association process.

✓ Note: The Machine Stop button must be in the UP position before activating and using the console remote.

1. Stand near the base unit with the remote OFF and power removed from the base unit (disconnect the P1 and P2 cables or turn the source power OFF).
2. Release the STOP button on the PG handheld by twisting and pulling it up.
3. Push and hold switches S1 and S7 UP. All four LEDs light solid.
4. Observe the LEDs. When TX begins to blink, power up the base unit while continuing to hold switches S1 and S7. When all four LEDs light solid, release switches S1 and S7.

A successful association is indicated when LEDs TX and RX are rapidly blinking in unison.

To Dissociate (see Figure 12)
The PG remote must be OFF, and the base unit must have power removed before starting the Dissociation process.

✓ Note: The Machine Stop button must be in the UP position before activating and using the console remote.

1. Stand near the base unit with the remote OFF and power removed from the base unit (disconnect the P1 and P2 cables or turn the source power OFF).
2. Release the STOP button on the PG handheld by twisting and pulling it up.
3. Push and hold switches SW1 UP and SW7 DOWN. All four LEDs light solid.
4. Observe the LEDs. When TX begins to blink, power up the base unit while continuing to hold switches S1 and S7. When all four LEDs light solid, release S1 and S7.

✓ Note: Be aware that all remote associations to the base unit are now broken.
To prevent inadvertent machine movement, be sure to remove power from the Base Unit before attempting to Associate or Dissociate.

To Associate (see Figure 13)

Associate mode is used to establish the communications link between the 18-button handheld remote and base unit on a 1-to-1 basis.

To Associate:

- There must be a clear line of sight between the handheld and the base unit
- The handheld must be near the base unit—within six feet
- Both units must be OFF (powered down)

Turn off the 18-button handheld by pressing its OFF button when the unit is ON, or by allowing the unit to time-out. Off is indicated when none of the LEDs are active when any function button is pressed. Safely power down the SmarT base unit by disconnecting the power source from the unit.

Figure 13. XX-218 Associate Mode

Note: Observe LED states while performing the following procedure.

1. Remove power from the base unit (disconnect the P1 and P2 cables or turn the source power OFF), and turn off the handheld.
2. Stand near the base unit with the handheld in a clear, unobstructed line-of-sight.
3. Press and hold button 2, then press and hold button 1. Hold both buttons simultaneously.
4. Wait until the amber LED2 goes out. Release the two buttons being held.
5. Press and release button B16. The GREEN LED1 and the RED LED3 turn ON.
6. Power up the base unit.
If the Association is successful, the AMBER LED2 will flash. If communications are not established following the Associate procedure, repeat until communication between the handheld and base unit is achieved.

To Dissociate (see Figure 14)

![Figure 14. XX-218 Dissociate Mode](image)

✓ **Note:** Observe LED states while performing the following procedure.

1. Remove power from the base unit (disconnect the P1 and P2 cables or turn the source power OFF), and turn off the handheld.
2. Stand near the base unit with the handheld in a clear, unobstructed line-of-sight.
3. Press and hold button 2, then press and hold button 1. Hold both buttons simultaneously.
4. Wait until the amber LED2 goes out. Release the two buttons being held.
5. Press and release button B17. The GREEN LED1 and the RED LED3 turn **ON**.
6. Power up the base unit.

If dissociation is successful, green LED1 on the handheld remote will continually flash (TX), indicating that the handheld and the base unit are not communicating.